

Abstract

The present invention relates to a parking assistance for a vehicle, characterized in that it, in autonomous parking on a path for parking the vehicle, the driver of the vehicle is assisted in a parking maneuver on the path for parking the vehicle by means of a steering torque applied to the steering wheel, whereby the driver is guided on the path for parking the vehicle by at least one artificial steering stop, preferably one or two artificial steering stops, and the path for parking the vehicle is divided into a maneuvering path in the area of a parking space and an approach path situated prior to the maneuvering path in accordance with the starting position of the vehicle.